iCar

iTrain for Modelcars



Manual 5.0

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1 Introduction

This manual is written to assist users to configure and use iCar. The descriptions aims to control digital modelcars.

The first part will describe the general way of working and the most important parameters of the program. Then the definition and control of the cars is described. Finally the switchboard and according elements wil be declared.

For driving trains in combination with cars we have to refer in addition to the iTrain manual.

When you start working with iTrain for the first time you will need to know some basic concepts of the program.

1.1 The main window

An ordinary screen in iTrain may look like the following :



In this screen we can identify three main areas:

- 1. The overviews in the upper left corner give an overview of the status of every car and give immediate control over their main functions;
- 2. The control or throttle in the lower left corner gives more control over all the settings of a car and is meant to control it in detail;
- 3. The switchboard on the right side is a simplified drawing of your layout, in which you see where your cars are and what the state of all turnouts, signals and other objects is. You also can change the state of all objects.

1.2 Main objects

In iTrain we distinguish several types of objects for cars:

- Interface refers to the connection with a command station or other device to control the layout;
- Feedback refers to sensors in the lane that detect if part of a lane is occupied or not;
- Accessory switchable objects;
 - Turnout is the switch to either join multiple tracks in one or split one track into multiple tracks;
 - Signal/Trafficlight may either refer to actual traffic lights on the layout or only to virtual traffic lights on the switchboard to indicate if a car should stop or is allowed to drive;
 - Crossing is a crossing between the road and the railroad;



- Car refers to a specific car;
- Car type refers to a category of cars with similar behaviour;
- Lane is a part of a track (not including turnouts) where more cars can drive at the same time;
- Intersection is a gathering of lanes most of the time including traffic lights;
- Switchboard is the presentation of the layout in which most of the objects can be switched or viewed.

1.3 Naming

In iTrain, all cars, turnouts, traffic lights and all other objects have a name that is unique per object type. You do not have to remember all the addresses, because you can give every object a useful name. It is recommended keeping the names short and using a naming convention that you understand. Every object can also have a description to give a more descriptive name to your own wishes, but the description may be left empty as well.

For example, for the name of a car you can use the company name like DHL or GLS followed by a number of the car, for example DHL01.

For the names of lanes and accessories you can use logical numbers prefixed by an identification of the position on the layout.

Note: It is recommended naming your objects independently of the actual address of the object and choosing a more logical name based on the location in the layout. The address will be displayed between parentheses behind the name. In many cases you may need it (such as with selection boxes).

1.4 File handling

After you have started iTrain for the first time, no file has been associated with your project so you have to save your project with a specific name. It is recommended using the extension .tcdz for iTrain files (tcdz =Train Control Data Zip), for example layout.tcdz, and saving them in the folder iTrain/layouts in your home directory and not in the folder Applications (or Program Files for Windows). On Mac OS X this folder will not be created by the installer so you have to create it manually once.

Note: On OS X the .tcdz files will get a special icon to indicate that it is an iTrain file and you can double-click it to open the file.

The next time you start the program, it will automatically try to load the same project. The project name will be shown in the title bar of the main window together with the full path to the file and the iTrain version in which it was created.

When closing the program the project will be saved automatically, unless you have chosen to do that manually. This will not only save the definitions of all objects, but also the current state of the layout (where are the trains and what was the last state of all accessories).

Backup

Before saving a file, the previous file (with the same name) will be moved to a backup subdirectory and the date and time will be added to the file name. This way you always have a backup of the previous states of your layout in case something goes wrong. The name of the backup files have the following format that includes the original name followed by the word backup, the date and time of creation of the backup and the version of iTrain with which it has been saved.

layout_backup-20191209-190742_v5.0.0.tcdz

To restore a backup, just open the file from the backup subdirectory in iTrain and the original file name and path will be restored. So it is not necessary to copy and rename files from the backup



directory. The backup directory may fill up fast with every save, but the files are generally small compared to the available disk space. You could clean them up if you want, but in general it is not necessary.

Recent files

The menu item 'Open recent files' shows a list of up to 10 files that have been opened recently. You can go back to an earlier opened file quickly by selecting it from the list, but do save the current file first if you have made modifications that you want to store.

Import

The import allows you to open a file as well. But it will import only the cars. The import will add this part to your already loaded file. The import dialog contains a tab, showing all cars which can be imported. You can now select the cars you want to import and also indicate whether they should be imported actively or inactively. Possible conflicts with existing cars are displayed in the last 2 columns "Duplicate" and "Addresses in use with".

Export

The export allows you to export the most important objects (cars, accessories, feedbacks and lanes) as different .csv files (tab separated, encoding UTF-8) that can be read immediately by a spreadsheet program. In the export these .csv files will be bundled as a zip-file. Because every object can have only one line with columns for their properties, only the single value properties of an object will be exported and not the complex properties that are lists or tables in themselves.

A more detailed description can be found in the iTrain5 manual.

Note: The exported files are only for analysis or bookkeeping and cannot be imported by iTrain.

1.5 Online

When you are working with the program sometimes you only want to change your configuration where at other moments you are really controlling the cars on your layout. In the second case you will need a connection to the control device and when this is done the program is 'online'. In the right lower corner of the screen you can see whether you are 'Online' or 'Offline'. This is the current status. With the button on the toolbar you can change the status to 'Online' (text below button is 'Connect') or 'Offline' (text below button is 'Disconnect').

Note: It is always recommended selecting 'Disconnect' or exit iTrain before turning off your control device so that it can disconnect correctly. If you accidentally turn it off before going offline then check if the program did detect it or else do it manually instead.

1.6 License

iTrain is a commercial product and runs by default in demo mode. You are limited to 3 cars and 32 accessories and 32 feedbacks. This allows you to test iTrain on a small demo layout. To make use of all features available in iTrain you have to register and you will get a license that is coupled with your e-mail address. To enter your license number go to main menu "Options => Enter license key".



Type or copy your e-mail address that you used to get a license and paste your license key into the 'License Key' box by using <Ctrl> or <Command> + <V> key or the popup menu. It is not recommended typing it manually.



If your registration succeeded you will see the about box with your license type, name, contact information, e-mail and optionally the end date of the license.



1.7 Project

Now you are ready to enter your model road into iTrain. We call this the project. All the project data can be entered via the different items in the 'Edit' menu and will be saved in the project file except for the preferences that will be stored somewhere on your computer and will remain the same even if you change the project.

First check the preferences and the settings and choose the interface before you continue with entering your layout. The next step could be entering cars to test your connection, but this can be deferred to a later stage as well. A good strategy is to first draw the whole layout, then assign all the turnouts, traffic lights, feedback and lanes to the drawing and finish with the cars.



2 Preferences

The preferences are settings that apply to all projects and are saved on the computer itself in an application specific location. You can find them in the iTrain menu on Mac OS X or at the bottom of the 'Edit' menu on other operating systems.

2.1 General

Prefere	nces				×
General Sv	ritchboard	Interface	Network	Remote Control	
☑ Auto se		ng s on startup			
Look & Feel Language Length unit Speed unit	English (t		·		
Base path	C: \Users	\ajgra			Find
			ОК	Cancel	

In the 'General' tab you can change some specific settings of the behaviour of iTrain. It is possible to save the project when closing iTrain without asking for confirmation. By default a check is done if a newer version of iTrain is available at startup. If your computer is never connected to a network you can turn this off.

Look & Feel

Every operating system has its own look & feel and sometimes you can even choose themes. iTrain by default follows the look & feel of the operating system, but it is possible to choose another one for consistency among computers. The recommended cross platform look & feel is 'Nimbus' that is now used by default on Linux. Changes to the look & feel will not be active immediately, but only after a restart of iTrain.

Language

The iTrain user interface is available in multiple languages. By default it will choose the same language as the operating system and this is called 'System Default', but you can change it to a language you prefer. The changes will not be active directly, but only after restarting iTrain, because the user interface has to be reloaded.

Length unit

The length unit specifies what kind of measure is used throughout iTrain for displaying length. It is recommended to use centimeters, because that will fit naturally with the scale of most models and is also used internally. Millimeters, meters, inches and feet are also selectable options. Length values are floating point values so you can have 51.5cm or 0.515m. In every length input box in the program you can always enter a value in another unit by adding the unit to the value. It is automatically converted to the unit specified in this preference after hitting the <ENTER> key. The possible suffixes for length units are 'mm', 'cm', 'dm', 'm', 'in' and 'ft'. When you do not specify a unit in a length input box, the default specified in the preferences is assumed.

Speed unit

The speed unit specifies what kind of measure is used for displaying speed corrected for scale throughout the application. The natural unit would be km/h or mph, but also m/s is possible. Speed unit values are also floating point values. In every speed input box in the program you can always enter a value in another unit by adding the unit to the value. It is automatically converted to the unit specified in this preference after hitting the <ENTER> key. The possible suffixes for speed units are 'cm/s', 'm/s', 'km/h' and 'mph'.

Base path

This is the path where the iTrain data is stored. The path refers to the location where iTrain is located containing the images, layouts and sounds folders.



2.2 Switchboard

Preferences			>
General Switchboard Interface	Network	Remote Control	
Default grid			
Look Cessic v			
[OK	Cancel	

The 'Switchboard' tab has some generic settings for the switchboard that apply to all projects. The option 'Default grid' decides if a new switchboard or the switchboards in a newly opened project will be shown with a grid. It will not affect current switchboards, because you configure it for the existing switchboard via the popup menu. To automatically use the maximum allowed zoom that does not need scrolling for newly opened projects, select 'Default fit'.

The look or appearance is a set of colours, line widths and text size used to draw the layout. There are three looks available:

- Classic a white background and drawn as in all previous versions;
- Contrast with a light gray background that is easier for the eyes and makes the colours better identifiable, somewhat bigger font for better readability;
- Dark using a dark background and lighter track lines so colours of feedbacks and signals have better contrast.

2.3 Interface

Grouping

Grouping is another way of displaying the address of an accessory or feedback with two numbers and a dot in the middle (<module>.<output> format). In iTrain every object has its own absolute number, but in many command systems addresses are written with group or module numbers and sub numbers. A few examples:

• the address **1** is written as **1.1** when used with grouping.

• the address **33** is written as **2.1** when used with grouping or module size **32**.

The general formula is: **address = (module number** - 1) * **group size + output number** A grouping of 32 e.g. is used for OM32 and OC32.

General	Switchboard	Interface	Network	Remot	e Control		
Address	grouping —						
Accesso	ry addresses	Default 🗸					
Feedba	k addresses	Default 🗸					
Blo	xk addresses	Default 🗸					
Boos	ter addresses	Default 🗸					



3 Settings

The project specific settings are saved in the configuration file and will be the same on every computer using this project. You can configure the settings via menu "Edit => Settings".

3.1 General

🚺 Sett	ings			Х
General	Options C	omment		
Scale	H0 (1:87)		~	
Time -				
Factor	6 ≑			
Start	06:00:00			
End	22:00:00			
	OK		Cancel]

Scale

The most important setting is the track scale that is used for the speed and distance calculations. For modelcars this will normally be H0 (1:87) or N (1:160).

Time

Factor is used to indicate how fast the time on the layout should go. A value> 1 will move time faster. "Start" and "End" indicates which parts of a day will be used.

3.2 Options

'Always set accessory' will switch all the assecorries when starting iCar. This will avoid assecorries to be in a different state then iCar expects.

The option 'Reset turnouts after release' will setback turnouts always in the startposition. This can also be defined for each individual turnout.

Settings	Х
General Options Comment	
Always set accessory	
Reset turnouts after release	
OK Cancel	



4 Interface

The program communicates via USB with the device for modelcars. Selecting the right interface will give the possibilities for controlling modelcars.

🎒 Inte	rface Ec	litor (1/1)		Υ <u>΄</u>	×	nterface E	ditor (1/1)			×
Active New York State S	5	Name MCC	Description HCC (LICC)	Name (MCC Description (MCC (UCCI) Type S MCC (UCC) Control type Vehicles Accessories Peedbacks General Connection Specific Image Comment Send stop at disconnect Activation time 250 ms (s) Activation time 250 ms (s) Reedbacks Switch off delay 50 ms (s) Switch off delay 50 ms (s)			Name BLDB	Description BDrectored Bus	Name BD/B Description BD/rectional Bus Type \$ BD/rectional Bus Type \$ BD/rectional Bus Control type Vehides Control type Vehides General Comment Send stop at disconnect Accessories Default protocol DCC > Activate all accessories after connecting Feedbads Switch off delay 50 ms \$	
							copy	- Child	- approximation Provide C	

Via the menu "Edit => Interface" you can select the 'Interface' that is connected to your computer. In case of controlling cars this should be MCC (UCCI), Dinamo (RMU) or BiDirectional Bus (BiDiB). The 'Description' field allows you to change the description of the interface in the application. On the tab at the bottom you can see how the interface will be displayed including the number in front of it.

For use of multiple interfaces, please consult the iTrain 5.0 manual.

By default an interface for modelcars will control the vehicles and accessories, and read the feedbacks in iTrain. Although it is possible to restrict the 'Control types', we recommend to use them all for controlling cars.

More specific interface settings have been divided over multiple tabs in top called 'General', 'Connection', 'Specific' and 'Image'.

4.1 General

The option "Send stop at disconnect" will send a stop signal to the central station when the program stops so that cars do not continue to drive uncontrolled.

The 'Activation time' is the default time between the activation of an accessory and its release. This can be overridden per accessory.

By default all accessories are activated when going Online so the state on your layout and in iTrain will be identical. Switching this off can cause collisions of cars while switches might not be at the state iTrain is expecting.

Feedbacks are the eyes of the program and it is important they deliver good results. In some cases it is necessary to filter the raw input to remove short spikes because of bad contacts.

The 'Switch on delay' is the time a feedback needs to be on before the feedback sees it as on. The same holds for 'Switch off delay', so an off is only seen after some time without an on. In general it is important to keep the 'Switch on delay' short, because most actions are based on a feedback going on and it might delay the action. In most cases you can leave it to zero, but if you use it then take a small value (<50ms).

The 'Switch off delay' for cars is also critical, then this indicates the next car can pass. While cars can drive very close to each other, short contact loss might cause a collision. Therefore a short delay is preferred to unwanted release. Common values for 'Switch off delay' are in the range 100-500ms.



This feedback filtering is the default setting for all feedbacks attached to this interface. It can be overridden for any individual feedback. This is useful if you combine feedback modules with different characteristics.

Note: Filtering the feedback output also results in fewer transitions from on to off and back again and will improve the overall performance of the application, because actions and checks will not be executed unnecessarily.

4.2 Connection



The carsystem has a serial interface by means of a USB connector. Using the USB connector you have to install a Virtual Serial Port (VCP) driver: https://www.ftdichip.com/Drivers/VCP.htm.

On the 'Connection' tab you always have to select a port. Using the 'Refresh' button will give a recent list of choices for ports. All other settings have a default value for this interface.

4.3 Specific

The tab called 'Specific' contains in case of the MCC (UCCI) interface only the 'Transmission interval'. This is configurable, but in general keep it on the default value of 5ms.

For the Dinamo (RMU) interface and BiDiB there are some more variables besides the 'Transmission interval'. For cars normally the standard values will be used.

4.4 Status

The status of all interfaces is shown on the right side of the status bar. It shows the name or description of the interface including the indication $\boxed{\text{MCC(UCC)} \bullet}$ (Online) or $\boxed{\text{MCC(UCC)} \bullet}$ (Offline). By hovering over the name of the interface it will show between bracket the letters VAF or a subset indicating the interface has been configured to control (V = Vehicles; A = Accessories; F = Feedbacks).



5 Cars

5.1 Create or edit a car

To get into the 'Car editor' you go to the menu "Edit => cars" or press <Ctrl> + <F10>.



At the left side is the list of cars known by iTrain. This is typically your whole collection. In the 'Active' column you can indicate which cars are currently available on the layout, so that elsewhere in the program where you have to select a car only the active cars are shown.

To manage the list of cars you use the buttons below the list. You can add a new car by using the 'New' or 'Copy' button. In case of 'Copy' the currently selected car is used as a template and its definitions are copied to the new car. Only the name is adapted to create a unique name. The 'Delete' button removes the currently selected car from the list.

On the right side you find the car editor to change all car definitions. You have to fill in at least a name, decoder type, interface, address and speed to be able to drive the car. The buttons below the editor give some extra control over the editor:

- The 'Apply' button applies changes you made in the input fields. This will immediately be reflected in all windows. If you select another car the previous selected car will automatically be applied;
- The 'Reset' button discards the changes you made in the editor and reloads the fields with the current value. After an 'Apply' a reset will only discard changes made after the 'Apply';
- The 'Clear' button clears all the fields.

5.2 Car definition

Give the car a unique 'Name' and a corresponding 'Description'. Keep the 'Name' as short as possible because it keeps the presentation in the switchboard clear.

It is important to specify the 'Car type' correctly when driving automatically, because the type will determine the behaviour and routes of the car.

The following 'Car types' have been defined:

- Default (no specific type car)
- Truck
- Bus
- Garbage
- Ambulance
- Police
- Fire



Specifying the 'Length' of the car is necessary in order to calculate the space needed in a lane and also the stopposition of the next car.

In the 'Decoder' section you can specify the decoder 'Type' (MCC or DCC), the 'Interface' (the carsystem) and the 'Address'. The field 'Node' at the BiDiB interface is preferably left blank for optimum operation.

Image

Image	Speed	Functions	Configuration	Options	Routes	Permissions	Comment	
File 0	DneDrive	/Documente	n/MCC/iTrain/im	ages/DHL	jpg			Eind
	DHL							
	(Te	-DHL						
		360 x 160 p	nivels.					
	Delete							

The first tab 'Image' allows you to add an image to your car. An image has a preferred size of 360x160 pixels that is prepared for high-resolution displays, but images of 180x80 pixels are still allowed.

Use the 'Find' button to add an images. Standard is the search at the installed 'Base path'. It is recommended to save all images on this place.

Large images are always downscaled to fit in 360x160 pixels before they are used in iTrain. If your image is much larger, you can first scale it down in another program, but you can also let iTrain do it.

Speed

The second tab 'Speed' shows the speed related properties. The upper part shows the real speed characteristics in km/h of the car against the decoder steps. You can use the speed measurement via menu "View => Speed Measurements=> Cars" (described later) to do the actual speed measurements in iTrain or manually enter the values if you calibrate outside of the program.



At the bottom, the maximum speeds when driving automatically can be specified. Uncheck the box 'Maximum' if there is no maximum speed for the car.

Functions

Image	Speed	Functions	Configuration	Options	Routes	Permission	s Commer	nt	
Use	Кеу	Туре		Desc	ription	D	uration		Momentary
\square	f0	% Front/n	ear light	Lights	front/rea	r		-	
	f1	🚺 Brake li	ght	Brake	light			-	
\square	f2	🔅 o Turn ind	dicator left	Indica	ator left			-	
\square	f3	o 🔅 Turn ind	dicator right	Indica	tor right			-	
\square	f4	Q Light		High b	beam			-	
\square	f5	o Interior	light	Side li	ghts			-	
	f6							-	
	f7							-	

On the third tab 'Functions' you can assign the car functions to the correct f-keys. MCC decoders always have four basic functions (light, brakes, indicator left and indicator right). OpenCar decoders control the brakelights by themselves. Therefor only 3 basic functions (lights and indicators) will be used. Depending on the decoder additional free functions can be defined.

A function can be assigned to an f-key by checking the first column 'Use' and selecting a type from the 'Type' column. Automatically, a default description will appear that you can edit to describe the function in more detail. The 'Momentary' box checked means that the function will only be activated as long as the corresponding button or key is pressed, for example for bright light.

Configuration

Image	Spee	d Functions	Configuration	Options	Routes	Permissions	Comment	
Use	Nr	Value	Тур	e		Description		
\checkmark	1		Sho	rt address				^
	2		Mini	num speed	ł			
\checkmark	3		Aco	eleration				
\checkmark	4		Dec	eleration				
\checkmark	5		Max	imum spee	d			
\checkmark	6		Mide	le speed				
\checkmark	7		Vers	ion				
\checkmark	8		Ven	dor				
	9							
	10							

The fourth tab 'Configuration' is used to define which CV values of a car can be read and written. This option is only used for DCC decoders. With 'Used' you can indicate which CVs can be accessed with the decoder programming. 'Value' is the last known setting of the CV as stored in iTrain. Under 'Description' it can be indicated in iTrain what the CV entails. It is only a description that is used in iTrain.



Options

The fifth tab 'Options' shows some extra options for cars. The option 'Auto light on/off' gives the possibility to switch on the lights of a car when driving automatically. If this option is not checked, the light of a car must always be switched manually or via a defined action.

Inertia simulation

The inertia simulation works by delaying the speed steps sent to the decoder. Single steps are executed almost immediately, but when a speed change requires multiple decoder step changes, the intermediate steps are sent with a delay between the step change as specified. You can set the inertia simulation separately for the acceleration and braking. The first value is the step delay and the second value the step size. To disable iTrain inertia simulation, uncheck the boxes. When activating a car function called 'Direct Control', the iTrain inertia simulation is also disabled for that car.

Auto light on/o		augri optiona	Routes Permissio	ns comment	
nertia simulation -					
Acceleration	Step delay	500 ms 🖨	Step size 1	2	
Braking	Step delay	250 ms 🜲	Step size 1	2	
Feedback offset -					
Reed contact	Front	0.5 cm 💲			
Light barrier					
Reaction delay					
	Forward 2	200.0 ms ≑			
Period					
	Maintenance	40.0 h ≑	Fuel	5.0 h ≑	

Note: Good values for the inertia simulation are typically between 100ms and 500ms. Do not use lower values than 100ms, because that does not allow a speed command to be sent by the 'Interface' and processed by the car before another speed command will be sent.

Feedback Offset

When using occupancy feedbacks these are normally triggered by the magnet of the car. In some cars this magnet is not at the frontline of the car (e.g. by busses). So when the feedback is triggered the car might already somewhat further than expected. To correct this error, you can specify the offset from the front of the car.

Reaction Delay

The reaction delay is only used when using 'Positions' (described later). With 'Positions' you can use exact positions (for example in cm) in the lane to stop a car based on time/distance calculations. Normally there will be an offset error at the entry of a lane, because calculations are relative and not absolute. By experimenting with the reaction delay you can correct this offset for multiple lanes.

Period

Here you can specify after how many hours a car needs maintenance and how long a car can run with a full battery. The times are measured or calculated based on the driving time of a car. The battery symbol can be shown in the car overview and thus indicating that a car must drive to a charging point. In addition to showing, the signal can also be used as a condition to start an action. The maintenance time is for information only and is not yet being used.

Routes

Image	Speed	Functions	Configuration	Options	Routes	Permissions	Comment
Select	Active	Name				Description	
		Bus1				Busroute 1	
		Truck				Route Truck	
		FT				Firetruck	

Here a selection of active routes can be made that may apply to this car. The routes are defined elsewhere (see 6.10) and possibly made active.



Permissions

Image	Speed	Functions	Configuration	Options	Routes	Permissions	Comment	
 No 	access to				Only	access to		
Тур	Name			Descriptio	n		Direction	
				ane inside			Both	
				Lane outsid			Both	
1	10.00							
								Move up
								Move down
								Remove
								Insert
								Append
Lane	< No lar	ie >						\sim
			Apply	Re	set	Glear		
			14517	rve.		200		

The tab 'Permissions' is to exclude access ('No access to') or only allow access to ('Only access to') specific lanes for this car. Use the buttons on the right to add rows and use the lane input box at the bottom the change the lane of the selected row. In some cases the lane should/should not be accessible in a specific direction. For those cases change the 'Direction' column as required.

The last tab 'Comment' allows you to add comments about the car. You can use it to write maintenance remarks, info about the car in real life or anything else you find useful.

5.3 Car control

To control one or more cars, you can use the overview, 'Car control' or grid.

Overview

Icon	Addr	Name	Actual	Tank	Position	Lane		Route
THE .	3	FTP	31.3 km/h	62.96	25 cm	L OL	3	FT
A COLOR	9	DHL	0.0 km/h	85 %	5 cm	L BB	8	Truck
for the	105	MCC	0.0 km/h	100 %	-	-	0	-
-	106	GLS	0.0 km/h	12 %	86 cm	L OL	0	•

The car overview in the upper left corner shows all active cars with some of the important settings. By default a small image of the car, the name, the actual speed, the signal facing the car and the current lane are shown. It is easy to add more information in this verview. In the example besides also the decodernumber, status of battery, position in the lane and activated route is presented. The **O** button will start automatic driving for a car and the **O** button will stop automatic driving.

Which property is shown in the columns of the overview can be changed by right click on table heading and selecting 'View Columns'. It is also possible to automatically sort the cars on some of its more static properties (Address, Name, Description, Type, Route, Decoder and Interface).



Icon	Nr	Name	Step	· · · · ·	· · · · ·			1								
-	11	B11	0	View colu	umns 🕨	⊻	Icon	0-								
	8	Beer	0	Sort on	Þ	✓	Address	6 -								
	4	BW	0	0,0 km/h	0,0	✓	Name	ō -								
- ten	9	DHL	9	36,3 km/h	35,0		Description	0 -								
	3	HW	0	0,0 km/h	0,0		Туре	ō -								
38	10	Stbs	9	40,2 km/h	40,0		Profile	0 -								
6	2	ZKW	0	0,0 km/h	0,0	\checkmark	Speed step	ō -								
		1				\checkmark	Real speed	-								
						-	Desired speed									
							Direction									
							Time									
							Ime									
							Distance		Icon	Nr	Name	Sten			Lane	
									Icon	Nr 11	Name B11	Step	View	columns 🕨	Lane	
						✓	Distance	Þ	Icon	Nr 11 8	Name B11 Beer	Step 0	View		Lane Address	
comot	tive W	agon Car	III			✓ ✓	Distance Control	•		11	811	0	Sort	on 🕨	As 🔳	
		agon Car					Distance Control Traffic light			11 8	B11 Beer	0			Address	
	ive W DHL	agon Car	m			•	Distance Control Traffic light Lane	•		11 8 4	B11 Beer BW	0 0 0	Sort 0,0 km/h	on 🕨	Address Name	
		agon Car	m			•	Distance Control Traffic light Lane Stop / Start			11 8 4 9	B11 Beer BW DHL	0 0 0 9	Sort 0,0 km/h 36,3 km/h	on 0,0 kr 35,0 kr	Address Address Name Description	•
		agon Car				✓✓✓	Distance Control Traffic light Lane Stop / Start Route			11 8 4 9 3	B11 Beer BW DHL HW	0 0 0 9 0	Sort 0,0 km/h 36,3 km/h 0,0 km/h	on → 0,0 kr 35,0 kr 0,0 kr	Address Address Name Description Type	

Control

The 'Car control' is used to have full control over the car while at the same time having all the information available in a nice way. It consists of three tabs.



The first tab 'Control' is the main tab for directly controlling the car. To select a car in the 'Car control', you can use the drop-down box (only the active cars are shown) in the left upper corner or you can select via the 'Car overview' by double click on the car, drag (from overview) and drop (at 'Car control') or select a row with a car in the overview and press <ENTER>. You will get a picture of the car, the current

signal state the car is facing a trafficlight in the lane, a speed control, the current lane, info, the decoder step and all the car function states.

To modify the speed there are several options:

- Move the slider that represents the decoder steps. Double click will stop the car;
- Use the scroll-wheel of the mouse while the mouse is positioned in the 'Car control' to change the speed in decoder steps;
- Use the '+'key to increase the speed and the '-'key to decrease the speed. The speed will be changed to the previous or next speed that can be divided by 5;
- Use the number (0-9)keys on the keyboard to set the speed from 0 to 90km/h in steps of 10km/h, and use the Shift key in combination with these keys to set the speed from 100 to 120km/h.

The speedometer shows the real speed in km/h according to the speed measurements. In case of no speed measurements the maximum decoder speed is considered to be 120km/h. In the gray rectangle of the speedometer you see two speeds: the desired speed at the top and the real speed that the car is driving below. These two speeds might be different if the desired speed cannot be matched exactly with a decoder step. In that case the decoder step is chosen whose real



speed closely matches the desired speed while at the same time not topping it by more than 5km/h to prevent it from going much faster than desired.

Functions can be changed by pressing the button with the function icon. For many function types a special key is reserved, as can be seen in the popup menu attached to the 'Car control' or 'Overview' (both right mouse click). Momentary functions will only be activated as long as the button or key is down.



All other functions will change their state when pressing the button or key.

The drop-down box at the right upper corner is for setting the control type of the car. There are three options:

- Manual control: the program will not influence the car in anyway, but it still tries to follow where the car is on the layout;
- Semi-automatic control: the program will only reduce the speed of a car whe the car needs to stop;
- Automatic control: the program automatically sets the speed to the maximum allowed by the car in combination with the lane, and stops the car if necessary. The D button will start automatic driving for a car and the D button will stop automatic driving.

As extra information the facing trafficlight for the driver is shown by a symbol between the car image and the speedometer. If no signal has been defined on the layout on that position, 'Sight*' will be shown.

Below the car image, the current lane and info is displayed. The latter, among other things, displays reports about incorrect driving of cars.

Options

Car	-	DHL						•
Route	< No ro	ute >						•
Profile	0	1	2	3	4	5	6	7
				Reset tota	als			
Contro		Comme	.+					

The second tab 'Options' shows properties that less frequently changes. The first input is to select the car in control, just as on the first tab. The second field 'Route' can be used to select an available route for this type of car.

You can select one of the 8 profiles (0-7) from the MCC decoder driving a car. Standard is profile 1. For Opencar decoders the profile is not used.

The button 'Reset totals' is to reset the total time and distance travelled by a car to zero.

The third tab contains the comments for a car. This is the same content then the 'Car editor'.

5.4 Car Grid

In stead of having one 'Car control' it is possible to have multiple ones. They will be shown in a grid, so next to each other and/or above each other (no feature at standard version).

Sar grid	a sense areas			-2 1	×
DHL	🔹 😰 Automatic 🔹	Stbs : Citybus	🔹 😰 Automatic 👻	ZKW : Ambulance	▼ Semi-automatic ▼
Lane ABu	0 0 0 70 0 0 0 0 70 0	Lane Induit	0 400/402 100 0 20 400/402 100 0 20 20 20 20	Lane No lane	a 20 40 10 20 40 10 20 40 10 10 2041 10 10 2041 10 10 2041 10 10 10 10 10 10 10 10
Info -	♥ 3408,4 ♥	Info -	◆ 2.875.2 ◆	Info -	♥ 1.181.5 ♥
Step	· · · · · · · · · · · · · · · · · · ·	Step	0 10 15	Step 0 5	10 15
Q 🕨 😻 🐗 🚺 🖸		Q 🕨 💿 👒 💶 🖉		Q 🕨 🕫 🕫 💶 🔒	
Control Options Comment		Control Options Comment		Control Options Comment	

To add or remove extra car controls , one car control needs to have focus (press F3) and you can use the <Alt> + <cursor> keys to size the grid.



<Alt> + <cursor right> will add controls to the right (columns) and <Alt> + <cursor down> will add to the bottom (rows). To remove car controls use <Alt>+<cursor left> for a column and <Alt>+<cursor up> for a row.

The focussed car control has a border drawn around the car image. To navigate between the car controls use <Shift >+ <cursor> keys. To change the selected car within a car control you can use the <ENTER> key to popup the list with cars and select one with the cursor keys followed by pressing <ENTER>.

5.5 Programming decoders

Each decoder has a list of configuration variables that determine the behavior. A simple example is the address of the decoder, but there are also complicated settings. There are many tools available to configure the decoder the way you want. Programming decoders in iTrain is not included to replace all these tools. It is intended as a basic programming tool to make the most common settings without closing the interface in iTrain.

Configuration

The first step in programming a decoder is to specify the configuration.



The properties of a car have a 'Configuration' tab with a table. All CV numbers are present in this table. You first have to indicate for which numbers values are present (by checking them) and what the type of the value is (by double-clicking and selecting from a list). You can also enter your own description in the last column. It is not immediately necessary to enter a value, but if you already know the value, it is recommended to do this immediately, so your complete administration is at one place.

Values are always stored internally as decimal values, but depending on the type, the values will be displayed in a different format if that makes interpretation easier (eg a supplier is translated into a name). There is always the possibility to view the value in decimal, binary, hexadecimal or ascii format via the tooltip. When entering a value, a decimal value is expected by default, unless you put a prefix before it. The prefix "b" means that a binary value follows, "h", "x", "#" or "\$" means a hexadecimal value and a quotation mark means a letter (so "A" is the same as 65).

It is a lot of work to enter the configuration for each car. By using the popup menu of the table you can do it a bit faster by copying the definitions from other cars. Select the rows that you want to copy and paste them into another configuration that uses the same numbers. There are also a few standard templates for the most common variables / parameters for DCC.

R	Delete	Delete
<u>_</u>	Сору	Ctrl+C
Ó	Paste	Ctrl+V
	DCC defa	ault

Programmingtool



If you have made a configuration for a car and iTrain supports programming with your interface (central or programming train), you can read and/or write values with the programming help in iTrain. You can find this programming help in the menu "Show" -> "Decoder programming". You must then use the submenu to choose which type of object you want to program.

First you have to select the car. Then the table with the configuration will appear, but only with the relevant numbers. Then select the interface with which you want to program from a



list of usable interfaces. The 'Program Track' or 'Main Track' (= PoM) options do not apply to cars.

Now you can start exchanging data between iTrain and the decoder by choosing the rows and then pressing 'Read' or 'Write'.

Note: It is necessary to first create the configuration of the car, as described in the previous section, before you can read or write anything. This way you know what you read or write.

While reading or writing the values, a green arrow will appear in the 'Value' column, which means that the process is working on this line. If the action is unsuccessful (for example because there is no response within a certain time), a red icon will

Nr	Value	Description
1	🔿 3	
5	2 5	
17	192	
18	203	
29	32	

appear to indicate that the value is probably not written or read.

It is possible to adjust the values in the table before you write a value or start reading from the decoder, but the values are only stored with the car after the 'Apply' button has been pressed. In case you accidentally read the values of another decoder, you can therefore restore the original values in the table by pressing the 'Reset' button. If you want to clear all values before you read, press the 'Empty' button.

Special values

The configuration of some DCC variables requires some extra attention, as they are often used and available on almost any decoder.

Long address

In the past, most decoders only had a short address (7-bit) with values from 1-127 (sometimes even limited to 2 digits, therefore 1-99). Later the option came to use a long 4-digit address. To specify such a long address, 2 variables are needed. For DCC these are CV17 and CV18 and these must have the types 'Long address high' and 'Long address low'. To enter the address you must make a division with remainder to split the address into a quotient and a residual value:

CV17 = (address divided by 256) + 192 CV18 = (address modulo 256)

For example, at address 360 you must use the following: CV17 = 1 + 192 = 193, CV18 = 104, (L = 1 * 256 + 104 = 360).

In the table, CV17 will now be shown as L256 + and CV18 as 104. The L means that you have correctly added the value 192, which means Lang address. The + at the end indicates that the following value (CV18) must be added to get the full address.

To actually use this long address, the correct bit in CV29 must be set to 1. Sometimes this happens automatically, so to be sure, read CV29 just after writing CV17 and CV18.

5.6 Speed measurements

In all the settings of speed a normalized speed in km/h is used. This makes it easier to compare speeds of different cars. By default the program does not know which decoder speed step belongs to which real speed and it assumes that the maximum decoder step is 120km/h. All steps in between are linearly interpolated. Of course this is rarely the case and you have to measure the speeds of your cars for correct behaviour when driving automatically.

To calibrate the speed of your car, you can use the special calibration tool by going to menu 'View => Speed measurements => Cars'. The car in the main car control will be selected already.



× Speed measurements Car DHL \sim Type Two feedbacks ~ \sim FB-7 : Feedback 7 Feedback 1 Feedback 2 FB-19 : Feedback 19 \sim Distance 95 cm 🖨 from 1 to 2 95 cm ≑ from 2 to 1 Speed measurements H0 (1:87) Step Value 55 0.0 km/h 1 0.0 km/h 50 10.0 km/h 45 13.5 km/h 3 40 17.2 km/h 35 5 20.8 km/h 30 25.1 km/h 7 27.4 km/h 25 32.8 km/h 20 9 36.3 km/h 15 39.8 km/h 10 10-11 43.5 km/h 47.1 km/h 12 13 52.5 km/h 10 12 14 Clear Control Previous Next Start Stop

Туре

Speed measurements are all based on a car driving with a fixed speed between two positions and dividing the distance by the time it takes to drive this distance. The value is then corrected with the model scale.

For cars we use most of the time the method of two feedbacks with some distance in between. One measurement starts when feedback 1 is activated and is ready when feedback 2 is activated. It is also possible to advance measurements with a speedometer. This must then be defined with type 'Device'.

Measuring

To do the actual speed measurements, select one or more rows with speed steps in the measurements table (left side) and press 'Start'. All buttons will be disabled except for the 'Stop' button until all

selected steps have been measured. A clock icon will appear in front of the value that will be measured. When the first feedback is activated the icon will change into a green arrow to indicate that measurement of this value has actually started. When the second feedback is activated the individual step measurement has been done and the icon will change into a 'checked' icon. When multiple rows have been selected the next value will be measured until all values have been measured.

Note: cars should be able to drive in a circle so measurement of different steps can be done automatically.

Note: The order of selection is important when selecting multiple rows and determines if the steps are measured from low to high or high to low. It is preferable to measure from high to low speeds.

At any time during the measurements you can press 'Stop' to abort. When doing the speed measurements one at a time, you can use the 'Next' or 'Previous' button to measure the speed for the next or previous decoder step.

Note: Values can also be edited manually. To clean a value, you have to select a row and press <DELETE>.

It is not always necessary to measure all steps, and values can be left empty or zero. Always measure the first step for which the car starts to move. This is the minimum step. All decoder steps before the minimum will not be used by automatic control and are considered idle steps. The last step with a value greater than zero is considered to be the maximum step. All steps that are left empty or zero between the minimum and maximum speed will be interpolated as soon as the 'Apply' button is pressed.

Note: All speed measurements should increase with every step to make them useful in controlling the car. You can check this easily in the graph. If values are not increasing, they will be sorted after pressing 'Apply' and after the optional interpolations.

Note: The car function 'Direct control' will be activated when doing speed measurements to disable the inertia simulation in the decoder. The car will get to the measured speed faster and it will brake faster giving a more precise measurement and taking up less track space for high speed measurements. Take care that the 'Direct control' function does not reduce the speed. In that case change the type of the function to 'Slow'.



6 Switchboard

The switchboard is intended to control all the accessories and feedbacks in your layout and to see what is happening with every car. As every layout is different in size, the switchboard has some ways to handle a large layout on the screen:

- 1. Multiple tabs to show different parts of your layout directly;
- 2. Separate zoom control per tab;
- 3. An optional overview per tab;
- 4. The option to use a 'Wide' layout view.

To zoom in on the switchboard, there are several options:

- Use the scroll wheel of the mouse in combination with the <Ctrl> or <Command> key to zoom in or out at the location of the mouse pointer in the grid;
- Use the popup menu via the right mouse button (or use <Ctrl> + click) and go to the 'Zoom' sub menu.

The grid in the switchboard can be switched on and off via the popup menu 'Show grid' or <CTRL>+<G>.

Quality

			50%	
			75%	
			100%	
			125%	
			150%	
			200%	
			300%	
\checkmark	Anti-Alias		400%	
	Interpolated		Fit	Ctrl+B
	Show Grid	Ctrl+G	Fit width	
0	Zoom	•	Fit height	Ctrl+E
۲	No overview			
	Overview north			
	Overview west			
	Overview south			
	Overview east			
	Overview in window			

The option 'Anti-Alias' should always be switched on unless your graphics processor is quite old and slow. It will make all drawing more smooth. It is checked by default.

The option 'Interpolated' enhances the quality of imported images in the switchboard when being scaled. It will degrade the drawing performance and is only recommended on systems with very good graphics performance. It is unchecked by default.

'Zoom' provides a number of standard options for zooming in / out. In addition, 'Fit' can be used to present the layout plan in maximum size in the switchboard. The other 2 options will present the layout as far as possible in width or height.

6.1 Overview



This overview option in the popup menu of the switchboard adds an extra overview pane at one side of the switchboard (for example at the bottom with 'Overview south') or in a separate window.



In the overview the whole switchboard is shown with a rectangular box that shows which part has been zoomed in. This is very useful if your layout is quite big and you want to control only a part of it, but at the same time keep an eye on the whole and be able to switch to another part very easily. There are two ways to manipulate the visible part in the switchboard via the overview:

- You can drag the box in the overview to move the zoomed in area;
- You can select an area in the overview with the mouse (starting with a selection outside the current box) to show what should be shown in the switchboard. After selecting an area it might change to keep aspect ratio of the switchboard space.

Layout view

Next to the standard layout there is also a wide layout where the whole width of the window is used for the switchboard and the car controls are put below the switchboard. This makes more space for all the columns in the 'Car overview' and is also useful for layouts that are very wide but do not need the full height of the screen. It is available via the menu 'View => Layout => Wide'.

6.2 Controlling switchboard

Every accessory (like a turnout or traffic light) or feedback can be (de)selected or changed by single clicking it. For different objects the behaviour might be slightly different:

For turnouts it will change from straight to branch or the other way. A special case is a three

way turnout that is actually considered as being two turnouts that cooperate. If the state of one of the turnouts is branch it will go to straight. If the state of both turnouts is straight the change depends on which side you click and it will only change this side of the turnout. In case you want to select a state directly, just press down the mouse button on the turnout until a popup with all states appears, and select one.

Traffic lights will change between red and green. In case you want to select a state directly, just press down the mouse button on the traffic light until a popup with all the states appears,

and select one.

Feedbacks are toggled by clicking when the control system is offline, but if your control system is online it will set the feedback according to the state read from the interface and you cannot change it.

Name		Length	Position	Move up
1.00	FTP : Firetruck Platform	11.5 cm	69.9 a	Move down
-23	GLS	12 cm	86.5 a	Remove
				Insert
			i i	Append

Lanes cannot be switched and in this case a dialog pops up to select a car that is in the lane (or no car)

You can also attach a car to a lane by drag & drop. You either select a car from the 'Car control' or 'Car overview', or you select a car from the switchboard itself and drop it onto a feedback in the lane.

It is also possible to select a car on the switchboard and move it to

another lane.

With 'Insert' or 'Add', cars can be placed in the lane. Make sure the position is not known and the order of cars is correct!

Selecting a car in the list and then selecting 'Remove' will remove the car from the lane. Make sure that the car is actually off the road because it is no longer seen when driving automatically. The 'Up' and 'Down' options provide the option to adjust the order of cars. The advice is not to use this because it can completely disrupt driving behavior.



6.3 Create or edit the switchboard

To create a new switchboard or to edit a current one, select from the menu 'Edit => Switchboard' or press <Ctrl> + <F4>. If you do this for the first time you will be asked to enter a name for the first tab. You can modify it later, so if you do not know or only need one tab, just enter 'Main'.



You will now see the above screen. The switchboard is at the centre. At the top you see a toolbar with some actions. On the right side is the toolbar with all the elements you can put on the switchboard.

On the left side there is an optional 'Browser' with all objects currently defined in iTrain that may or have been attached to the switchboard.

In the grid you see the cursor shown as a red rectangle that you move with the cursor keys or by clicking in the grid with the mouse.

To draw elements in the switchboard the preferred way of working is to select an element on the right (by mouse or better with the keyboard), turn it into the right position using the <Left> tor <Right> arrow key and then go to the switchboard and press <Space> to add the element. You can continue by selecting another cell with the arrow keys and pressing <Space> again. Elements can be rotated in the drawing as well as on the element toolbar.

To change the size of the grid, you have to use the <Alt> key in combination with the arrow keys: <Left> or <Up> to decrease the grid size in horizontal and vertical direction; <Right> and <Down> to increase the grid size in horizontal and vertical direction. Elements outside the grid are not removed but are just not visible anymore.

It is also possible to double click the element on the element toolbar to add an element to the switchboard. However, this slows down the drawing process when having to add multiple elements, because you continuously have to change the focus between toolbar and switchboard. Try to learn some of the key commands and you will be able to draw your layout very quickly. In Appendix A of the iTrain manual all the key commands available are described.

When using the keyboard to enter commands, the focus is important. The best practice is to keep the focus on the switchboard (highlighted cursor) and select elements from the toolbar via key combinations. When you are holding the <Ctrl> or <Command> key you are navigating through the toolbar:

- Cursor Up/Down to select the items on the element toolbar;
- Cursor <Left> or <R> key to turn the selected element on the toolbar counterclockwise in the preferred direction;
- Cursor <Right> or <T> key to turn the selected element on the toolbar clockwise in the preferred direction.

From the switchboard you can now easily edit the grid:

- <Cursor> keys to move the cursor in the grid;
- <Space> key to add an element from the toolbar to the switchboard;



- <R> or <T> key to turn an element in the switchboard counterclockwise or clockwise;
- <Alt> + <cursor> keys to change the size of the grid;
- <Shift> + <cursor> keys to select an area of the switchboard;
- <Shift> + <Alt> + <cursor> keys to change the size of elements that can cover multiple cells;
- <Shift> + <Control> or <Command> + <cursor> keys to move a selected element or area over the switchboard;
- or <Backspace> key to delete an element. Only the element on top will be deleted if one cell is selected. If the selection contains multiple cells, all layers will be deleted;

=	Browser	0	
B	Clear		
Ŧ	Compress	С	
I	Draw	Space	
T	Remove	Delete	
	Undo	Ctrl+Z	
\mathcal{X}	Cut	Ctrl+X	
	Сору	Ctrl+C	
Ľ.	Paste	Ctrl+V	
Ċ	Turn clockwise	т	
3	Turn counter clockwise	R	
0	Assign to group	G	
0	Remove from group	Shift+G	
U	Connect	N	
6	Zoom		;

- <Shift> + or <Backspace> key to delete an element. Only the element below will be deleted if one cell is selected and two elements are drawn on top of each other. If the selection contains multiple cells all layers will be deleted;
- <Ctrl> or <Command> + <X> to cut the current selection and copy it to the clipboard so that it can be pasted later;
- <Ctrl> or <Command> + <C> to copy the current selection to the clipboard so that it can be pasted later;
- <Ctrl> or <Command> + <V> to paste the elements on the clipboard at the cursor. If the elements do not appear where they should do, you can move them again with <Shift> +
 <Ctrl> or <Command> key + <cursor> keys or delete them with the or <Backspace> key to undo the paste operation;
- <Ctrl> or <Command> + <Z> to undo a move, a cut or a delete. Once the selection changes, you cannot undo it anymore.

Note: Once an area (more than one cell) of the switchboard has been selected, you cannot use the curve and turnout elements from the toolbar anymore. Select a single cell to be able to use all elements again.

Tip: The popup menu (click right mouse button) of the switchboard in edit mode contains some of these commands (with their key equivalents). The same zoom functionality is available in edit mode, only without the overview function.

6.3.1 Toolbar



The toolbar on the right may contain more elements than your screen can display. The elements are grouped. Via the popup menu (right click) you can select which groups are visible. If your space is limited, it is recommended to deselect some of the elements. For cars are available 'Road elements', 'Road connections', 'Others road',

'Control elements' and 'Draw elements'.

Once the focus is on an element in the toolbar, the following key commands can be used:

- Cursor <Up/Down> to select the elements;
- Cursor <Left> or <R> key to turn the selected element counterclockwise in the preferred direction;
- Cursor <Right> or <T> key to turn the selected element clockwise in the preferred direction.

The road elements are meant to draw the lanes. The first element is the straight lane and the second and third are both a curved lane. The fourth element is the arrow that indicates the direction the car is driving. Each lane should at least contain one arrow for direction. The fifth element is a closing element, if a lane is continued on another tab. This closing element can be used as a button to jump



to another tab when all the lane definitions (explained later) are set correctly. The next element can display a deviating maximum speed form the lane or indicate a lane being inactive.

Note: If the car is allowed to drive in both directions, just select one direction or select the preferred direction, but do not put two arrows in the opposite direction. In the lane properties (explained later), you can define which directions are allowed in the lane and if necessary the element will change into a double arrow automatically.

The turnout elements are just a preselection of some of the possible types of turnouts. You can change the type later on by double clicking the turnout and selecting a type.

The 'Others road' are elements that are drawn into a road element. The first one represents the lane. It is used as the display of the lane to show the cars into the lane and it may cover more than one cell. In edit mode it will show the name of the lane if the zoom level is 125% or more. The second element is a feedback on your layout.

Next is the traffic light and is drawn on a straight lane so that it is always clear to which lane it belongs.

The last element is the intersection. This is used to define the lanes coming together into an intersection. The intersection is used to control the traffic lights corresponding to the lanes.

Tip: The lane element grows dynamically and may cover more than one cell when a name appears into it. Take this into account when drawing your layout, and do not put other non-road elements next to it that may be covered and will not visible anymore at that time.

Note: Traffic lights belong to the lane in which the car will stop and not to the lane they are protecting. This is a more practical decision to make it easier to define a situation where lanes are connected by a turnout and the signal is placed before the turnout, but is protecting the lane after the turnout.

6.3.2 Layers

There are no specific elements for tunnels and bridges, because you can draw elements on top of each other. When you draw a new element over another element in the same direction, then it will replace the current element. If you draw it in a different direction, then it will be drawn on top of another element with a kind of transparent gray bridge element.



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If only a single cell has been selected, then actions like delete, move, copy will act on the element on top. If more than one cell has been selected, the actions will act on all layers.

Tip: In case you see the gray layer drawn on some elements, but there is no purpose for two layers, you probably have put two elements on top of each other, but afterwards turned the element on top in the same direction as the one below. This is an error and may give unwanted results later on. You can correct it by selecting the cell and

press <Shift> + to remove the element below. Now the gray layer should disappear.

When you control the layout, it is no problem to switch an element (for example a turnout) that is below a normal track element. Only the top most switchable element is switched and so nonswitchable elements on top of switchable elements are not a problem, but prevent two switchable elements on top of each other if you want to be able to control them manually.



6.3.3 Browser

The browser on the left gives on overview of all the control objects defined in iTrain that can be or are attached to elements in the switchboard. You can assign control objects to a switchboard element by drag & drop. Normally, you immediately create a control object together with the switchboard element.

Tip: The browser can be hidden by using the 'Browser' button on the toolbar to get more space for the switchboard. Hitting the same button again will bring up the 'Browser' again.

Туре	Addr	Name	Descri	ption	
r	1.1	Bus In	Bussto	p entrance	
Y	-	Bus Ex	Busstop exit		
Υ	1.4	ToCLFO	Turnou	t Crossi	
r	-	ToCRFO	Turnou	t Crossi	
Υ	-	ToCLFI	Turnou	t Crossi	
r	1.2	ToCRFI	Turnou	t Crossi	
Υ	1.3	ToCMFL	Turnou	t Crossi	
r	-	ToCMFR	Turnou	t Crossi	
r	-	ToCLBO	Turnou	t Crossi	
Υ	1.5	ToCRBO	Turnou	t Crossi	
r	1.6	ToCLBI	Turnou	t Crossi	
Y	-	ToCRBI	Turnou	t Crossi	
r	-	ToCMBL	Turnou	t Crossi	
Y	1.8	ToCMBR	Turnou	t Crossi	
X	-	OFL	Crossing for lef		
X		CFR	Crossin	ig for right	
メメメ	-	CFM	Crossin	g for mi	
X		CBL	Crossing behin		
X	-	CBR	Crossin	ig behin	
X		CBM	Crossin	ıg behin	
	1.15	TICFL	Traffic	light cro	
	1.18	TICFR	Traffic	light cro	
	1.21	TICFM	Traffic	light cro	
	1.24	TICBL	Traffic	light cro	
	1.27	TICBR	Traffic	light cro	
	1.30	TICBM	Traffic	light cro	
Feedbac	k Accessory	Track Route		Booster	

In the browser you can rearrange control objects by drag & drop within the browser or you sort the objects by name by double-clicking on the column header. You can also remove control objects that are of no use anymore, but be careful with this, because once deleted you cannot restore them anymore. Removal of an object can be done via the popup menu (right click) or via the or <Backspace> key.

To select an object in the browser via the switchboard, you have to use <Ctrl> or <Command> + double-click on the element in the switchboard, or use <Ctrl> or <Command> + <Enter>. To find and select an associated element in the switchboard that is attached to an object in the browser, you can just double-click or select it and press <Enter> in the browser.

Tip: The overview can be hidden by pressing the 'Overview' button above the switchboard. This means there is more room for the switchboard. By pressing the same button again the overview will reappear.

6.3.4 Template

You can also create new control objects based on other control objects via the 'Template' action in the popup menu of the browser (right click). This is useful if you have to create multiple objects (for example turnouts or feedbacks) with almost the same name and description, but only with another number in it.

erties Space			
plate T			
ite			
TION			
IICFL			
Traffic light cro	ssing for left		
1 🖨 8	ind	₿₽	Correct existing o
	ОК	Cancel	
		te Delete plate T ste Traffic light crossing for left	te Delete plate T ste TICFL Traffic light crossing for left

You first select a control object from the browser that is used a base definition. Then you select 'Template' or you press <T>. In the presented dialog, you put a <#> character where the number should be inserted and in the 'Range' section you define the numbers that will be generated. In the example, 3 traffic lights will be created with the names VKR1, VKR2 and VKR3 and with a

description with the same number in it. Other properties of the base object will also be copied except for the ones that are naturally different, such as address, comment and other things that are unique for every object.

If the 'Correct existing one' flag is checked, then also existing control objects will be changed so that they now have the same properties as the reference.

Tip: The 'Template' action can be used to create many turnouts, traffic lights and feedbacks that are almost the same. You only have to add the address manually. Even if you have already created these more or less equal objects manually, you can use 'Template' to assure that.



6.4 Assign control objects

In the switch board you can draw turnouts, traffic lights, feedbacks and so on, but these drawing elements must be attached to their underlying control objects. For every control object there is only one object identified by its name, but it can be drawn multiple times on the switchboards, for example in different tabs.

You can create and/or attach the control object to its viewing element in the switchboard by doubleclicking the element. A dialog with two tabs will be shown:

- The first tab shows the properties of the board element or viewing element. You can select a control object from a list with already defined objects that you want to attach to it, or select the first entry starting with '<No...' if you want to define a new control object on the fly. If you change the selection it will automatically select the second tab to edit its properties.
- On the second tab you can change the properties of the selected control object or add the data of a new control object.

Signal properties	Signal properties	×
Board item Signal	Board item Signal	
Signal 📲 TICBR (1.27) : Traffic light crossing behind right 🗸 🗸	Name TICBR Description Traffic light crossing behind right	
Key No Key	Type 🚦 Traffic light 🗸 Initial State 📘 Stop	\sim
	Interface 5 MCC : MCC (UCCI) V Output device OM32	~
	Activation time 250 ms 🗘 🔽 Default	
	Address Single ~~ 1 1.27 -	
	State mapping Options Relay Configuration Comment	
	Enabled State Output	
	Stop 1 = 1.27	
	Go 2 = 1.28	
	Stop expected 3 = 1.29	
	Go expected 1 = 1.27	
	✓ Sight * 3 = 1.29	
OK Cancel	CK Cancel	

For example, when you double click a traffic light element, the 'Signal properties' dialog shows up. You have to select one from the drop down box or go to the second tab and enter a new signal.

Key mappings

To assign a key combination to an element, you can use the key mapping feature. Just select the 'Key' box and use the key combination you want to use, including modifier keys like <Shift>, <Ctrl>, <Alt> and <Command>. The text starting with 'Code' should change to represent the pressed key combination. This key combination is only valid on the tab of the switchboard where you assigned it, and doesn't belong to the control object itself. This way you can reuse key combinations on different tabs, for example for different stations.

Tip: Make sure you do not override an already existing system or program key combination, as you might get unexpected results. The <Esc> key is to remove an existing key combination and cannot be used in key combinations, because it is reserved to 'Stop' the system.

When you press 'Ok' on the dialog, the changes on the control object are stored in the object even if you later cancel the drawing in the switchboard editor.

6.5 Feedbacks

Feedbacks or sensors are the eyes of the system. They notify which part of the lane is occupied or what point on the lane was passed. In general, they can cannot see who was responsible for it, but only that something happened. Also see Appendix B for more background information on feedbacks.



🚺 Feedba	ck properties	×
Board item	Feedback	
	FB-19	
Description	Feedback 19	
Туре	- Reed contact V Inverted	
Interface	S MCC : MCC (UCCI) ~	
Address	83 🜩	
Options Co	mment	
Delay		
Switch on	0 ms 🗘 🔽 Default	
Switch off	50 ms 🔹 🔽 Default	
	OK Cancel	

Feedbacks have an address, an interface, a type and depending on the type a length. It is recommended to specify the type especially when it is of type 'Occupancy', because it will affect the behavior in lanes.

Only for a feedback of type 'Occupancy' you can enter a length of the feedback. This length is used to calculate the positions of the feedbacks in the lane and will be used to release previous lanes earlier.

-	Occupancy
-	Reed contact
I	Light barrier
•	Button
##	Value (8-bit)
•	Other

The 'Inverted' box allows to interpret the feedback the other way so that '0' is occupied and '1' is free. This is the default setting for a feedback of

type 'Light barrier'. When a feedback is inverted you see the inverted value in the switchboard. In the feedback monitor (mentioned later in this manual) you see the original input from the interface on the border/edge of the element and the inverted value at the inside. The 'Delay' of the feedback when switching them on or off is normally specified per interface, but you can override the values here for a specific feedback. When 'Default' is checked, you will see the default value in gray.

Tip: If the switchboard editor is zoomed in at least 200%, the feedback elements will show their name inside the red box. This is useful to check all your names in a big station on consistency.

6.6 Accessories

For all accessories you normally have to fill in the address box. If the accessory, for example a traffic light, does not really exist in your layout, but you want to add it to the switchboard (for example for hidden tracks) to show the internal state of the lane, use address zero or leave it empty.

🚯 Turno	ut pr	operties						×			
Board item	Turr	nout									
I	<u>N</u> ame	ToCRFI	ToCRFI								
<u>D</u> escri	ption	Turnout Crossin	g right for insid	e							
	Туре	Y Turnout Rig	ht	\sim	In	itial Stat	e 🛛 🖌 Straight	~			
Inte	rface	S MCC : MCC	(UCCI)	~	Outp	ut devio	e OC32 aspec	t v			
Activation	time		250 n	ns 🌲	2	Default					
Ad	dress	Single		~							
	1		1	2 🜩							
State map	ping	State feedback	Length + Spe	ed O	ptions	Relay	Configuration	Comment			
Enabled	Stat	e		Outp	ut		Output				
	1 s	traight 1 = 1.2 : Aspect 0 -									
	1	Iranch		2 = 1	.2 : Asp	oect 1	-				
L			ОК	Ca	ancel						

A turnout is an accessory with one address and two or three states.

The 'Activation time' box specifies the time between the activation of the accessory and the deactivation and must normally not be filled in. 'Default' must be selected to use the default of the interface as specified in the Interface editor. In some cases you might want to divert from the default settings and you can fill it in here.

The state mapping tab allows you to exactly specify the outputs on the decoder that will be activated for every state. For every accessory and turnout they will have a good default value so that you do not have to change it in most cases, but

you can if you want to. You can switch at most four outputs for every state change (for example, for a three way turnout you need two to set both sides). You can select from the addresses specified earlier. This way the mapping order is independent from the address and when you change the address the mapping will change accordingly.

The 'Enabled' column makes it possible to disable a state when it is no longer possible to select that state due to a mechanical or electrical defect (for example the coil doesn't work or a wire is broken) or when the state is not supported by your accessory. Just keep the output settings so that you can continue when the defect has been fixed. Disabling a state will have effect when changing the state in the switchboard manually, but also when

using car routes. Cars will not consider this state an option anymore and will choose another option if available (in case of alternative lanes).



In most cases you will use the 'State mapping' to change the outputs of a turnout that was connected the other way around. You can select the two states for which the outputs need to be swapped, and press <S> or use the popup menu. In case you only have two states, you don't have to select them first.

te feedback Length + Spe	ed Options Re	lay Configuration	Comment
Length		Speed	
	3.2 cm	Unrestricte	ed be
	3.8 cm	Restricted	ł.
OK	Cancel		
	Length	Length 3.2 cm 3.8 cm	3.2 cm Unrestricte 3.8 cm Restricter

The length of the various switch positions can be specified at the tab 'Length+ speed'. These values are used in the calculation of the position of a car in an alternating street. The speed in this tab is not used yet.

The 'Options' tab is only used for 'Always return to initial state after release' possibly used with cars. The other tabs are not used for cars.

6.6.1 Output Device

Dinamo/MCC users will see an extra 'Output Device' box to select if the accessory is controlled by an 'OM32' command, an 'OM32 Pulse' or an 'OC32 aspect'.

When selecting OM32 or OC32 only one address box will appear that refers to the first output used by the accessory. This address starts with value one for the first output (zero means no output used). So when an accessory is connected to an OC32 you can select to use either the OM32 commands generated by iTrain (easy, but less flexible) or the preprogrammed 'Aspects' in the OC32 that have been created with the OC32 config tool.

In case the accessory has been connected to an OM32, always select 'OM32' or 'OM32 Pulse'.

Tip: The 'OM32 Pulse' option generates only short pulses on the output like an ordinary accessory decoder or a PM32. You can use left over outputs on the OM32/OC32 for some accessories that need this, instead of buying a separate decoder.

BiDiB users can control accessories via DCC (both standard and via aspects), but they can also control these directly via an output on a module in BiDiB. The latter is called "Accessory (Bus)".

Turnout											
Name	Bus In	us In									
Description	Busstop ent	usstop entrance									
Туре	Turnou	Y Turnout Right V Initial State V Straight									
Interface S BiDIB : BiDirectional Bus V Output device						Default	~				
Node	<no item=""></no>			\sim							
Protoco	DCC			\sim	🗹 Default						
Activation time	2		250 m	S A	🗹 Default						
Address	Single			\sim							
1	L			1 🜩							
State mapping St	ate feedback	Length + Speed	Options	Relay	Configuration	Comment					
State		Length			Speed						
V Straight				3	cm	Unrestricted					
/ Branch				3.2	cm	Restricted					

When choosing "Accessory (Bus)" you cannot specify an address, but you must choose a module and a port number. The module is the BiDiB component and the port is the local port on this module starting at number zero. The module can be chosen from a list of available modules. This list will be refreshed every time a connection is made to a BiDiB system. The info button that stands for



'Identify' will cause an LED to flash on the module, but can only be used if there is a connection to the system.

6.6.2 Cross turnouts



The cross is a special object that normally has no address (leave it empty or zero), but it is considered a turnout, because it can have two states on the screen (but only one on the layout). iTrain needs to know which direction is supposed to be used so that it can lock the direction for a car. The length is used to determine the position of a car in the alternating street.

All other tabs (State feedback, Options and Comment) are not specific used for cars.

6.6.3 Crossing

The crossing is an element to indicate that the road crosses a track or waterway. Two types of crossings are available. The first is the railroad crossing and the second a bridge. In both cases they have the situation open and closed, but they differ in how they affect the car.

A railroad crossing will ensure that it is closed to cars when a train passes by. Cars will stop when the railroad crossing is closed.

In the case of a (movable) bridge, the car may not pass as long as the bridge is open. That is why the water shows (in blue) and a red line to indicate that this line may not be crossed.

The crossing is a switchboard element with a street element. It is possible to draw as many parallel lanes as you want, but you must specify the crossing on the 'Options' tab of all lanes that are part of the crossing to ensure that the crossing is also activated. This does not happen with automatic completion.

Board item	Cro	ssing						
	Name	RRCR						
Descr	iption	Railroad Crossin	9					
	Туре	Rairoad			~ 1	nitial State	Open	~
L	ength			3 cm	÷			
Inte	rface	S MCC : MCC	(UCCI)		~ Out	put device	OC32 aspect	~
Activation	n time		2	50 ms	÷	Default		
Ad	dress	Single			~			
	1			1.9	-			
State map	ping	State feedback	Options	Con	figuration	Comment		
Enabled	Stat	e			Output		Output	
	Open				1 = 1.9 : /	Aspect 0	-	
	Close	d			2 = 1.9 : /	Aspect 1	ŀ	
			OK		Cance	1		

Tip: It is recommended to apply the crossing only in shorter blocks, so that it does not close too quickly or opens too late, because if one of the blocks is reserved or occupied, it will close or stay closed.

The length indicates how long the road runs over the crossing. The other options are the same as with other accessories. On the 'Options' tab, you can enter the 'State delay' that indicates how long it takes you to get from one state to the other. In the case of a level crossing, this normally takes seconds and an intermediate state will be shown to indicate that the level crossing is opening or closing.

6.7 Lanes

Lanes are parts of the road where one or more cars can drive at the same time. iTrain will calculate the distances into a lane to allow more cars into a lane, depending of the length of a lane and the cars. The calculation of distances in combination with the length of the cars will avoid collisions.



Every lane is connected to other lanes directly or indirectly via turnouts, so each lane must know what its neighbouring lanes are on both sides. In iTrain the sides of a block are called 'Previous' and 'Next' indicating the default direction of the lane from 'Previous' to 'Next'.

To indicate a lane in the switchboard you need to assign multiple road elements (with Traffic lights and feedbacks) to a lane. An element with the white rectangle (in edit mode with an arrow for the text direction or the lanename) represents a lane. It is used to define the lane.



In edit mode you can assign other road elements to the lane by first selecting the lane element and pressing 'Assign to group' on the switchboard editor or the <G> key for grouping (see popup menu). Now all road elements that belong to that block got the colour orange. You can now assign extra road elements to the lane (not including turnouts) by selecting them and pressing 'Assign to group' on the switchboard editor or <G> again. You can also do it in one step by selecting all elements belonging to the lane (including the lane element) and pressing 'Assign to group' on the switchboard editor or <G>. To remove already assigned road elements from a lane, select them and use 'Remove from group' on the switchboard editor or <Shift> + <G>. By selecting an empty element cell and pressing 'Assign to group' on the switchboard editor or <G>, you turn off the highlighting of all elements belonging to the

lane.

Tip: The lane names will be displayed in the lane elements if the zoom level is 125% or more and you are in edit mode.

In switchboard edit mode all elements assigned to a lane have a kind of brown colour (colour in between orange and black). In a well-defined switchboard in edit mode, only the turnouts are black and maybe some tracks between turnouts not belonging to a lane. The arrow element shows the direction of the car in the lane. In edit mode it will show the default direction of the lane itself and you have to make sure that it points from the 'Previous side' to the 'Next side', not only to get good visual feedback about the direction of a car in the switchboard when controlling, but also to able to automatically fill in some of the properties of the lane. In case both directions are allowed, the darkest of the two arrows should point in the default direction from the 'Previous side' to the 'Next side'.

6.7.1 Edit

To edit the lane properties, you double click on the lane element or you select it and press the <Enter> key. A dialog with two main tabs will appear. In the first tab you see a simplified version of the switchboard with only the elements assigned to this lane. This can be used as a check to see if you did not forget to assign an element to the lane. It is this definition of the lane that is used later on to automatically fill in some of the properties of the lane, such as the feedbacks and traffic lights.





The text in a lane element will by default be horizontal so from left to right, but when the lane in the switchboard is drawn vertically you might want the text to be vertical as well. You can change the 'Text direction' to be 'Horizontal', 'Up' or 'Down'. The direction of the text will be displayed in the lane element with an arrow if the name of the lane is not displayed.

You can now select an already defined lane definition from the 'Lane' input or select '<No lane>' and define a new one on the second tab.

Lane properties

Lane properties	×
Board item Lane	
Name Bus	
Description Busstop	
Type Bus stop (30 km/h) V Length	20 cm ≑
Options Feedbacks Direction: Previous Direction: Next Comment	
Direction Uni-directional V	
Max count 🗸 1 🖨	
Weight 1	
Interface 5 MCC : MCC (UCCI) V	
Speed	
Dynamic 0.0 km/h 💠	
Wait Chance 100 % Minimum 15.0 s ↓ Maximum 30.0 s ↓	
Chance 100 % V Minimum 15.0 S V Maximum 30.0 S V	
Show All Auto fill	
OK Cancel	

The type of the lane affects what car may drive the lane and what the maximum speeds are.

Justifications per individual lane are possible via the 'Speed' tab, discussed later.

The 'City' type is intended for urban areas with a lower maximum speed; 'Countryside' and 'Highway' are intended for outside the urban area with resp. an average and high maximum speed.

The 'Emergency', 'Bus stop' and 'Trucks' types are intended for lanes in which resp. only emergency vehicles, buses and trucks may come. The 'Parking' type is specifically for parking spaces and 'Charge' for driving to a charging point, both with a low maximum speed.

A lane of type 'Charge' is not used for random driving. This can only be achieved with a fixed route.

The field 'Length' indicates the total length of the lane. This length is used to calculate the position of the cars within the lane. It is therefore important that this value is as accurately as possible.

Options

A number of generic lane settings can be defined in the 'Options' tab.

The property 'Direction' of the lane: A lane can be allowed to be driven in both directions or in just one direction. Even if it is allowed to travel in both directions in some cases, in most cases it should be used in one direction. This is called 'Preferred direction'. The single or preferred direction is always from 'Previous side' to 'Next side'. This 'Direction' setting directly effects the way the arrow element in the switchboard is drawn and it is also used by routes (described later) to determine what the preferred direction is.

With 'Max count' you can indicate how many cars can be in this lane at the same time. If this is 1 for a bus stop or parking space, only 1 vehicle is allowed and the lane is considered full. The next car must wait or pass by. In this way the traffic on the track can be distributed. If 'Max count' is switched off, there is no limit to the number of cars in the lane. The total length is then only taken into account, with cars connecting even if they are on turnouts.

'Weight' gives the possibility to make a difference in lane preference. A higher value means that this lane will be chosen more often compared to a lane with a lower value.

The property 'Interface' specifies the interface that is generating the signal for this lane. In case of the cars it will be UCCI (MCC), Dinamo (RMU) or BiDirectional Bus (BiDiB).



With 'Dynamic' a different maximum speed for a lane can be set. If an element for speed is included in the lane, the deviating setting will be shown there. In addition to manually, this option can also be controlled via actions.

Only with the 'Bus stop' and 'Parking' types can the options for stopping and the minimum and maximum waiting times be entered for options. When stopping, the system itself chooses a time between the minimum and maximum value and departs automatically again.

Feedbacks

It is important to know where a car is to be able to guarantee that it will not crash into another car. Therefore, every lane contains feedbacks or sensors to observe what is happening in the lane. The tab 'Feedbacks' shows all the available feedbacks with their position in the lane. To fill the list of feedbacks, you will normally use the button 'Auto fill'.

🕒 Lane pr	operties								×
Board item	Lane								
Name									
Description									
Туре	Bu	s stop (30 km/h)	✓ Ler	ngth					20 cm ≑
Options Fe	edbacks	Direction: Previous	Direction	: Next	Commer	nt			
Feedback			L	ength		Start	End		
- FB-12 (76) : Feed	back 12			-	4.8 cm		4.8 cm	
 FB-14 (78) : Feed	lback 14			-	16.6 cm	1	16.6 cm	
									Move up
									Move down
									Remove
									Insert
								ĺ	Append
									Fil
								-	
			Show	v All	Auto fill				
				_					
			OK		Cancel				

By specifying the positions of feedbacks in a lane you have more information about where a car is in the lane. The positions are used to evaluate the calculated positions of cars in time. Therefore the positions should be defined as precise as possible. The first feedback is also used to release the previous lane.

Per feedback, some extra columns are shown. At first the length of the feedback in case of a reed contact this is empty (zero). The next two columns show 'Start' and 'End' position of the feedback in the lane. While the length of the feedback is zero, the values in 'Start' and 'End' are the same. You only have to enter the value for start and then use the button 'Fill'.

Note: To fill in the position of the feedbacks in the lane it is necessary that the length of the lane has been specified first.

Entering the positions can be tedious. If the lengths of the feedbacks are filled in and you either have only one or two feedbacks, or the length of all the feedbacks together is equal to the lane length, you can use the 'Fill' button to fill them in automatically. Before you do that it is important that the order of feedbacks is correct (from 'Previous' to 'Next'), and if necessary, you can adjust the order by using the buttons 'Move up' and 'Move down'.

Direction tabs

A lane has two sides so in theory it can be driven in two directions. To distinguish these two directions both driving directions need to have a name. They are called 'Direction: Previous' and 'Direction: Next'.

- Direction: Previous is the direction from side 'Next' to side 'Previous' and in case the block has a preferred direction this is the non-preferred direction.
- Direction: Next is the direction from side 'Previous' to side 'Next' and the preferred direction in case of a preferred direction and the only allowed direction in case of a single direction lane.

Some important properties are specified per driving direction so there are two tabs with the same properties. It is necessary to specify them for both directions to correctly follow the car even when the lane is only used in one direction.



Tip:The 'Auto fill' button can fill in most of these properties automatically. It is however required that all the feedbacks, traffic lights, turnouts and neighboring lanes that will be chosen already have a name for correct results. So it is recommended to first assign names to all these control objects and then use the 'Auto fill' button to attach them to the lane.

🎒 Lane pr	operties				×
Board item	Lane				
Name	Bus				
Description	Busstop				
Туре	🔲 Bus st	op (30 km/h) 🗸 🗸	Length		20 cm 🗘
Options Fe	edbacks D	rection: Previous Direct	ion: Next Comment		
				Blink pos	ition -3 cm 🜩
Traffic light	< No signa	l>		 Stop pos 	ition 🛛 -4 cm ≑
First br	anch on sigh	t		Switch pos	ition 0 cm 🜩
Speed					
Positions			Maximum		Remove
		3 cm		20.0	Insert
		10 cm		15.0	Annend
		18 cm	I <u></u>	20.0	m/h
Lane					Turn direction
Item		Description	Side	Choice	Turn direction
Bus Ex		Busstop exit			
1 .	AB	Lane after busstop	Previous	Preferred	Dependent
		□s	now All Auto fill		
			DK Cancel		

The following fields can be filled in:

- 'Blink position': The position in the lane where the blinking light might be activated. You can enter the direct position (e.g. 29,5cm) or define a distance before the end of the lane (e.g. -30cm).
- 'Stop position': The last position in the lane where a car should or might stop. You can enter the direct position (e.g. 50,5cm) or define a distance before the end of the lane (e.g. -9cm). This position should always be behind the 'Blink position'.
- 'Switch position': The position in the lane where a turnout should be switched. Default this value can be zero.
- 'Traffic light': assigning the traffic light that might be at the end of the lane controlling the traffic.
- 'First branch on sight': when this box is checked a car can ignore redlight when turning right.

Speed

The default speeds in the lanes are specified in the general 'Settings', but these can be overridden in the box 'Speed' for every position in the lane. Using the buttons 'Insert' or 'Append' a new line while be attached before or after the selected line in the box 'Speed'. Using the button 'Remove' a selected line will be deleted.

Every line in this box contains a value 'position' and 'maximum'. These lines define the exact place in the lane ('position') where the corresponding speed ('maximum') should be driven.

In this way dynamic speed can be defined within a lane (e.g. reducing speed for a curve).

The last box in this tab will show the directions / next lanes which can be selected. If all control elements and lanes have been defined in the switch board, this box will automatically filled using the button 'Auto fill'.

Item	Description	Side	Choice	Turn direction
Bus Ex	Busstop exit			
🔪 🗖 LAB	Lane after busstop	Previous	Preferred	Dependent 🕔
				None
				Left
				Right

'Turn direction': this will affect the blinking lights of the car.

- o 'Dependent': blinking light will be activated when car turns left or right
- 'None': blinking light will not be used
- 'Left': blinking light left will always be used
- 'Right': blinking light right will always be used

The "Side" and "Choice" columns are not used for cars yet.



6.8 Deleting switchboard elements

When deleting an element from the switchboard that refers to a control object (for example a turnout, feedback, etc.) only the visual element is deleted and not the control object details. So if you accidentally delete a turnout element and then add a turnout element to the switchboard to replace it, you can still select the turnout object from the drop-down box. You should not define it again. To completely delete the control object, you have to remove it from the 'Browser', because then all references to this control object (for example in lanes) will be removed. However it is always preferable to edit and reuse a control object when something needs to be changed rather than to delete it and create a new one.

6.9 Adding/Modifying switchboard tabs

It is possible to add extra tabs or rename existing tabs by using the popup menu on the switchboard tab (right mouse click) in edit mode. The function always works on the active tab. The 'Insert' inserts at the selected tab, so before the current switchboard, and 'Add' appends a new tab at the end. If you want to change the order of the tabs later on, you can use 'Move left' or 'Move right' to move the current tab.

When using multiple tabs, the same accessory, feedback, track route and block elements might appear on different tabs. In that case it is necessary to define the objects only once and to attach them to the

switchboard elements on different tabs.

Tip: Often parts of the layout of two tabs have some overlap. It is possible to select an area and use 'copy' on one tab and 'paste' on another tab to copy parts to another tab. In that case the visual elements are copied, but references to the same accessory and feedback objects are used.

6.10 Car routes

Routes make it possible to automatically follow a path across the layout, using the lanes. Routes can exist on their own and can be assigned to one or more cars. To create or edit a route, go to the 'Edit' menu -> 'Car routes'.

🕒 Ro	ute editor (3)							×
		~	Name	Bus1				
Active	Name	Description	Description	Busrout	re1			
	Bus1 Truck	Busroute 1 Route Truck	Description	basioa	~-			
	FT	Firetruck	Items Opti	ons Co	mment			
				Туре	Name	Description	Direction	
					L BtF	Lane back to for	Next	
					LIL	Lane inside left	Next	
					L BtF	Lane back to for	Next	<u>R</u> emove
					L BeB	Lane befor bus	Next	Insert
					Bus	Busstop	Next	Append
			Lanes	100 %		30.0 s 🔺 Maximu	um 30.	0 \$ \$
			Direction I		\sim			1
			Type N	lame	Des	cription	Direction	<u>R</u> emove
								Insert
								Append
			Marker	None	 Sele 	ction In order	\sim	
N	ew Copy	Delete			Apply	Reget	<u>C</u> lear	

Routes are a list of lanes to follow. For cars, it is important to specify all lanes where the car passes. All stops must be indicated in a route, even if a lane normally already has a stop. In most cases, a



route is made to be repeatable. In that case you have to ensure that the last lane connects to a lane that appears earlier in the list (preferably at the start) so that the route can be picked up again from an earlier point. So if a route goes from lane A to B to C and beyond, the order of lanes in route A, B, C.

In the 'Items' tab you can press the 'Append' button (add at the end) or 'Insert' (for the selected element) to add an item to the list. Everything below this table applies to the selected item in this table. Each line in the top table shows the name and description of the lane of the item in the list. The symbols to the left of the name indicate that special things are happening in this lane as described below.

Wait

It is possible to wait in every lane along the route. A waiting time for a lane prevents reservations beyond this lane until the waiting time is over. A waiting time of zero means no waiting time. If a waiting time is specified, a clock symbol will appear in the second column of the table. *Note: There is no sense in assigning a waiting time to the first part of the route, because it only contains lanes from which you can start. It is useful to assign a waiting time to the last part of the route, because it indicates the time that is waited until a route is repeated or terminated.*

Markers

Markers are intended to indicate which parts of a route should be repeated if a repeat is specified. With no markers, just everything is repeated, so with simple routes they are not necessary. To add 'Start' and 'End' markers to the route, select a lane in the table and then choose the desired marker. The symbols will appear in the first column of the table. The number of repetitions can be put on the 'Options' tab and is described below.

With 'Selection' the route can be made more dynamic, because a lane is chosen from a list. This is indicated by an ' + ' in the third column of the table. A lane is selected based on the value of the 'Selection' field.

The options are:

• 'In order' means that the first or next lane from the list of lanes is selected, unless it is already occupied or reserved.

• 'Random selection' means that the list of lanes is first placed in random order. Then the first or next lane is chosen, unless it is already occupied or reserved.

• 'Optimal length' means that all lanes in the list are sorted by length from short to long and that lanes that are too short for this car are removed. Now the first or next lane is chosen again, unless it is already occupied or reserved. This is to prevent small cars from occupying a long lane. It is useful for shadow parking places.

6.11 Actions

🕒 Ad	tion edit	tor (6/64)							×
			~	Name	FT STOP				
Active	Туре	Name	Description	Description	Stop after de	aarb ya Cir	n her vale		
		FT STOP	Stop after de	Description	Stop after de	parture Fin	etruck		
ZZZZZ		FT START	Departure Fir	Condition	Execution Cor	mont			
	-	M30	Elektronic sig	Condition 1	Execution Cor	linent			
\checkmark	-	MG	Elektronic sig	Item		Туре	Change		
\checkmark	-	MX	Elektronic sig	🔲 'L IR' / 'i	FTP'	Lane	Enter		Move up
	-	Start	Start System			100.10	2.102		Move down
								-	
									Demous
								L	Remove
									Insert
									Append
								_	
					Anna -				
				Car	🎨 FTP : Fir	retruck Pla	tform		\sim
				Lane	IR : Lane inside	e right			~
									*
				Direction B	oth v S	State Ente	er		\sim
		-						-1	
N	ew	Copy	Delete		App	bly	Reset	<u>C</u> lear	



Actions can be started automatically from iTrain if predefined conditions are met. There are two tabs in which the action can be defined: 'Condition' and 'Execution'.

In this manual a brief description is written for iCar. For a more detailed description, reference is made to the iTrain5 manual.

6.11.1 Condition

Under the 'Condition' tab, several conditions are possible for cars to start an action:

- Time: on a predefined day and time;
- Feedback: one or more feedbacks are actived;
- Aspect
- Relay
- Transition
- Booster
- Battery: residual capacity of a battery for a certain car or all cars;
- Lane: when a car reserves, enters, releases, waits in or leaves a lane.

It is also possible to start an action independently of a condition with a button on the switchboard. The field 'Auto' can indicate whether the action is intended for a specific car or general. In the latter case it says '<all cars>'. With 'Type' you can indicate whether an action is for a specific type of car (eg Bus).

6.11.2 Execution

Under the 'Execution' tab, the steps associated with the action can be defined. Clicking on the field 'Type' with the right mouse button brings up a list of several types of steps that can be included in the action:

- Accessory: switching an accessory (eg turnout)
- Aspect: the direct switching of an aspect (only for OC32)
- Switch: switching a switch
- Signal: switching traffic lights
- Light: switching light (eg street lights)
- Sound: switching sound on / off
- Transition: operating a railway crossing or bridge
- Autoroute: starting or stopping a route
- Car function: operating a car function (eg flashing lights on)
- Auto shunt: direct control of the car
- Auto Permission: changing permissions for lanes
- Current car: assigning a current car to a lane
- Lane active: making a lane active or inactive
- Lane speed: adjusting or resetting the maximum speed
- Intersection: activating an intersection
- Time: the immediate setting of a time
- System: giving commands to the system (eg emergency stop)
- Command line: execution of a directly specified command



M30 MG MX	Description Stop after de Departure Fir Elektronic sig Elektronic sig Start System	Delay 11 6	Stop after depart Execution Comme Type 0 s Car route 0 s Car function 0 s Car route		. Off	Move up Move down
FT START M30 MG MX	Departure Fir Elektronic sig Elektronic sig Elektronic sig	Condition Delay 11	Execution Comme Type .0 s Car route .0 s Car function	nt Item 3'FTP' → ■ 'FTP' →	. Stop . Off	· · · ·
M30 MG MX	Elektronic sig Elektronic sig Elektronic sig	Delay 11 6	Type .0 s Car route .0 s Car function	Item 3 'FTP' →	. Stop . Off	· · · ·
MX	Elektronic sig	- 11	.0 s Car route .0 s Car function	(¥) 'FTP' → (*) 'FTP' →	. Stop . Off	· · · ·
		6	.0 s Car route .0 s Car function	\square 'FTP' \rightarrow	. Off	· · · ·
Start	Start System	6	.0 s Car function	\square 'FTP' \rightarrow	. Off	Move down
		-				Hove down
						Remove
						Insert
						Append
		Car	😻 FTP : Firetru	ick Platform		~
		Function	Flashing light blu	e		~
		State C	Off v Duration	0.0 s 🜩		
	Сару	Cgpy Delete	Function State C	Function Flashing light blue State Off V Duration	Function Flashing light blue State Off Duration 0.0 s €	Function Flashing light blue State Off V Duration 0.0 s 🗣

There are 4 columns in the list of actions. With 'Delay' you can indicate after how many seconds the next operation must start. With 'Type' the type of operation is displayed. 'Item' indicates which action is performed and with 'Change' what needs to be done. In the example above, the route is stopped 11 seconds after the 'FTP STOP' action is started. After 6 seconds the flashing lights are switched off and 2 seconds later a new route is started.

Switchboard

An action can be placed on the switchboard. Then you can start an action by clicking on it. If the action is running, the color will change and a number will be displayed with the number of active versions at that time. To interrupt and stop the started action, use 'Shift' + click. Now the action will not continue, but nothing will be reset to the original value, so be cautious about stopping current actions

6.12 Reservations

On a digital layout, you can run your cars anywhere via manual control. The computer adds lane control and makes sure that when you enter a lane, the cars in a lane will be protected for collisions. Here is where the reservations come in. A reservation reserves a positions in a lane for a car, and for other cars this position cannot be claimed. In the switchboard a reservation is indicated by a the name of the car in the 'lane element' and also in the 'feedback element' where the car is supposed to be or was last.

The same principle holds for reservations of turnouts that connect the lanes. When a car is in one lane and reserves the next lane, then it is also necessary to reserve the turnouts that connect those two lanes (if there are any). You can see that a turnout is reserved by a 'lock' symbol and the reserved colour (kind of yellow/orange). This prevents others from changing the turnout state until the turnout is released.

Reservations for lanes and the necessary turnouts will be done automatically. Reservations can be undone by holding the <Shift> key and clicking on a car in a lane element. This will remove the reservation in the actual lane.

6.12.1 Release lane

A car is normally in one lane and we call this the 'Control' lane. The feedback (position) in the lane is coloured red

and the name of the car is displayed in black letter in the lane and feedback element. Sometimes the tail of the car is still in another lane. This is called the 'Release' lane, as it will soon be released when the car has moved to the control lane.

Note: If a switch or crossing stays at the reserved state, it can be released manually by holding the <Shift> + <Alt> key and clicking at the switch or crossing.



6.12.2 Removing cars from lanes

We have seen a way lanes will be released automatically. There is another method to remove a car from a lane, by holding the <Shift> key and clicking on a lane or feedback element. This will remove the car from the lane. When there are more cars in a lane you can release all cars form the lane by holding the <Shift> key and clicking on the lane element. If you just want to release one car from the lane then hold the <Shift> key and click on the feedback element the car is at that moment.

6.12.3 Moving cars over or into the switchboard

When putting cars onto the layout or manually moving a car from one position on the layout to another position on the layout, you also have to change their position on the switchboard. To put a car from somewhere into a lane, you can drag a car from the 'Car control' or 'Car overview' or a block element in the Switchboard and drop it unto a feedback element.

6.12.4 Deactivating lane

A lane can be deactivated by holding <Ctrl> + <Alt> key and click on the lane element. The lane will colour light grey indicating it is inactive. If a speed element is included in the lane, it will show a red cross. No cars will enter this lane anymore.

To activate a lane the same key combination is used. The lane will colour dark grey indicating it is active.



7 Feedbacks, accessories and intersections

Next to the cars, car routes (not used yet), lanes and intersections you can also edit the 'Feedbacks', 'Accessories' and 'Intersections' via the 'Edit' menu without going to the switchboard first. This is useful to quickly change a definition or to manage the list of objects.

		~	Turnout								~	
ddr	Name	Description	Nar	me ToCLBO			-					Name FB-1
1.1		Busstop entrance	Descripti	ion Turnout Crossing	left behind outside		Туре	Addr	Name	Description		Description Feedback 1
-		Busstop exit	TV	/pe	nt v Initial S	tate Straight v	-	65		Feedback 1	^	
1.4		Turnout Crossing lef		in an arright		ate program	-	66	FB-2	Feedback 2		Type - Reed contact - Inverted
-		Turnout Crossing rig	Tatasfa	ace 5 MCC : MCC (0.0000 v. Outwateda	vice OC32 aspect v	-	67	FB-3	Feedback 3		
-	100011	Turnout Crossing lef	Interio	see s meet mee (vice OC32 aspect 🗸 🗸	-	68	FB-4	Feedback 4 Feedback 5		
1.7		Turnout Crossing rig					-	69 70	FB-5 FB-6	Feedback 5		Interface S MCC : MCC (UCCI) V
1.3		Turnout Crossing mi	Activation ti	ime	250 ms 🤤 🔽 Defau	it	-	70	FB-7	Feedback 6		
-	TO GE IN THE	Turnout Crossing mi					-	72	FB-8	Feedback 8		Address 65 🜩
-	100000	Turnout Crossing lef	Addre	ess None	\sim		-	73	FB-9	Feedback 9		Nuces US V
1.5		Turnout Crossing rig					-	74	FB-10	Feedback 10		Options Comment
1.6		Turnout Crossing lef	State mappir	ng State feedback I	Length + Speed Options Relay Co	onfiguration Comment	-	75	FB-11	Feedback 11		Contraction Contraction
-		Turnout Crossing rig	Enabled S	State	Output	Output	-	76	FB-12	Feedback 12		Delay
-		Turnout Crossing mi		Straight	1 = A1 : Aspect 0	-	-	77	FB-13	Feedback 13		
1.8		Turnout Crossing mi		Branch	2 = A1 : Aspect 1	-	-	78	FB-14	Feedback 14		Switch on 0 ms ≑ 🔽 Default
		Crossing for left				1	-	79	FB-15	Feedback 15		Switch off 50 ms 🔶 🔽 Default
-		Crossing for right					-	81	FB-17	Feedback 17		
	Griff	Crossing for middle					-	82	FB-18	Feedback 18		
-		Crossing behind left					-	83	FB-19	Feedback 19		
	CBR	Crossing behind right					-	84	FB-20	Feedback 20		
		Crossing behind middle					-	85	FB-21	Feedback 21	~	·
1.1		Traffic light crossing Traffic light crossing						New	Сору	Delete		Apply Reset Clear
1.1		Traffic light crossing									-	
1.2		Traffic light crossing										
1.2		Traffic light crossing										
1.2		Traffic light crossing										
1.5	o picom	rrame light crossing										

A dialog will appear with at the left side a list with the objects of a type (feedbacks or accessories) known by iTrain. To manage the list of objects you use the buttons below the list. You can add a new object by using the 'New' or 'Copy' button. In case of 'Copy' the currently selected object is used as a template and its definitions are

copied to the new one. Only the name is adapted to create a unique name. The 'Delete' button removes the currently selected object from the list.

Note: The 'Delete' button really deletes the control object and it will remove all references to this object from other control objects. Only delete an object if you are sure it is not used or referenced elsewhere or it could give unexpected results. Never delete a control object and create a new one, because you want to change the name or address.

On the right side you find the specific object editor to change all object definitions. Youhave to fill in at least a name and in many cases an address.

The buttons below the editor give some extra control over the editor:

The 'Apply' button applies changes you have made in the input fields. This will immediately be reflected in all windows. If you select another object, the previously selected object will automatically be applied;

The 'Reset' button discards the changes you made in the editor and reloads the fields with the current value. After an 'Apply' a reset will only discard changes made after the 'Apply'; The 'Clear' button clears all the fields.



7.1 Accessories

If you want to add a new accessory, there are two options:

- Use the 'New' button. There will be an entry field with 7 options. For cars, in particular 'Turnout', 'Signal' and 'Crossing' will be used;
- Use the 'Copy' button to create a new accessory based on an existing one. In that case, the type can no longer be changed, except for other types within the same type (for example, turnout type).

Properties

Turnout -									
N	lame	CFL							
Descrip	ption	Crossing for left							
	Туре	K Cross		\sim	Initial	State 🗋	Stra	ight BD	~
Inter	face	5 MCC : MCC	(UCCI)	~	Output o	levice C	M32		~
Activation	time		25) ms 🌲	🗸 Defa	sult			
Add	dress	None		~					
State map	ping	State feedback	Length + Speed	Option	ns Relay	Configu	ration	Comment	
Enabled	Stat	e	Outpu	ıt		c	Dutput		
\checkmark	١s	traight AC	1 = 0	0'		-			
	Υ.s	itraight BD	2 = 0	1'		-			

The editor allows you to edit properties of an object via the list of objects, but you need to look up the element again. It is also possible to edit an object directly by clicking the right mouse button while the mouse is above a specific object at the switchboard and selecting 'Properties' in the popup menus or context sensitive menu. You will get a dialog with only the specific object editor and you can change properties instantly. In the switchboard you can right click on the lane element and edit the lane (first option) directly.

In the 'Car overview' you can right click on a row and choose 'Properties' from the popup menu to edit the car directly.

7.2 Intersections



The editor allows to define the intersections. At the right side a name and description can be entered. At the tab 'Lanes' only the lanes ending into an intersections are defined. Most of the times these are the lanes containing traffic lights. The setting in the 'Nr' column can be used to determine how many lanes are released simultaneously. All lanes with the same number get green simultaneously. This can be used, for example, with opposite lanes at an intersection.

With 'Duration' the time can be set for the lane to turn green.

On the 'Options' tab you can set the time that is waited after the previous traffic light turns red and the next turns green. With the choice of 'Smart', only lanes with cars are considered, so that unnecessary waiting times are not created.

Intersections will be activated by an action or double click in the switchboard. Traffic lights on the intersection will be switched automatically.

Pressing the <Shift> key and click on the intersections will switch all the traffic lights in blinking position. The first car arriving at the intersections will pass through.



8 Extra tools

The extra tools are available via the 'View' menu.

8.1 Diagnosis

Diagnosis is a tool to find problems or inconsistencies in the object definitions of your job. After the tool is started up, the layout will be searched immediately and the results will be shown in a table.

	Diagnosis (6)			\times
		Start Stop Copy	(
	Туре	Description	Resource	Ot
0	Lane positions	Blink position outside of lane 'Bus'.	Bus	-
0	Lane positions	Blink position outside of lane 'L BB'.	L BB	-
0	Lane positions	Blink position outside of lane 'L BB'.	L BB	-
Â	Turnout	Turnout 'Bus Ex' has no length.	Bus Ex	-
Â	Turnout	Turnout 'CBL' has no length.	CBL	-
0	Car	Car 'Cmp' has no length.	Cmp	-

The list is first sorted by the severity and then by the type of problem. There are three main groups:

2 Error - This is wrong and must be resolved as quickly as possible.

Warning - This is probably not entirely good or incomplete. iTrain will work better if this is solved.

Information - This is not a problem at the moment, but can become a problem in the future.

Ideally, the list is empty, but it is no problem to keep some information messages in it as a reminder, for example to take speed measurements for inactive cars later.

You can click on a line to edit the underlying object or source. Use the 'Start' button to search again and the 'Stop' button to interrupt this. The 'Copy' button will put the selected rows on the clipboard so that they can be sent to the forum or in an email.

Tip: In the event of unexpected problems, it is recommended to first run the 'Diagnosis' to see if there is a problem before you ask for help. This saves yourself and us time.

In some cases you will not understand the problem directly from the description, because it must be kept short. It is then possible to search on the forum and if it is not found, ask for it on the forum. The number of checks during diagnosis will increase over time and it is therefore not possible to keep this up to date in the manual.

8.2 Feedback Monitor

The feedback monitor is an address based monitor tool for showing feedback states. A feedback monitor is available for every interface in the project that supports feedbacks.

🚺 Fee	dbac	k Mor	itor 1	: Dina	mo (R	MU)		1	1					Į	×
1.1	1.2	1.3	1.4	1.5	1.6	1.7	1.8	1 .9	1.10	1.11	1.12	1.13	1.14	1.15	1.16
1.17	1.18	1.19	1.20	1.21	1.22	1.23	1.24	1.25	1.26	1.27	1.28	1.29	1.30	1.31	1.32
1.33	1.34	1.35	1.36	1.37	1.38	1.39	1.40	1.41	1.42	1.43	1.44	1.45	1.46	1.47	1.48
1.49	1.50	1.51	1.52	1.53	1.54	1.55	1.56	1.57	1.58	1.59	1.60	1.61	1.62	1.63	1.64
1.65	1.66	1.67	1.68	1.69	1.70	1.71	1.72	1.73	1.74	1.75	1.76	1.77	1.78	1.79	1.80
1.81	1.82	1.83	1.84	1.85	1.86	1.87	1.88	1.89	1.90	1.91	1.92	1.93	1.94	1.95	1.96
1.97	1.98	1.99	1.100	1.101	1.102	1.103	1.104	1.105	1.106	1.107	1.108	1.109	1.110	1.111	1.112
1.113	1.114	1.115	1.116	1.117	1.118	1.119	1.120	1.121	1.122	1.123	1.124	1.125	1.126	1.127	1.128
2.1	2.2	2.3	2.4	2.5	2.6	2.7	2.8	2.9	2.10	2.11	2.12	2.13	2.14	2.15	2.16

Every button represents one feedback contact. If the button is filled it is connected with a feedback object in the program. A blue button means the feedback is activated. Open buttons are not related to feedback objects in the program, but still show the state they have received from the interface.

A popup menu (right mouse click or <Ctrl> key + click) allows you to increase/decrease the number of modules (also with < = > and < - > keys) or to toggle between 'Grouping' and absolute address mode (also the <A> key).



The feedback monitor automatically scales to fit the width of the window. By using the <F> key you fit the dialog window height to the current size of the feedback monitor.

Note: Using the same address for two or more feedbacks normally indicates an error situation, and the button will have a red border/edge. In case feedbacks share an address because they have been connected via a

relay (so that only one is actually wired at the same time), the button will have a yellow border/edge.

8.3 Layout

With Layout you can set the display to 'Standard' or 'Wide'. With 'Standard' the switchboard is shown on the right and the 'Car overview' and 'Control window' on the left. With the setting "Wide" the switchboard is presented over the entire width of the screen and the 'Car overview' and 'Control window' below it.

8.4 Additional views

This option is not available for the standard license.

The menu 'View => Extra' allows you to add a copy of a car overview, car grid or the switchboard in a separate window. You can put the extra views on a second monitor.

In case of the switchboard it shows the same layout and object states, but it allows you to view another tab at the same time or the same tab with another zoom level. This will be useful if you are controlling a large layout that does not fit on one screen.



Appendix A: Defined keys

For the defined keys we refer to the iTrain manual.

The following key combinations are the most used for controlling cars:

- Shift + Click on feedback => remove car from feedback; remains in lane
- Shift + Click on lane symbol => remove all (!) Cars from lane
- Shift + Click on turnout => cancel reservation of turnout
- Shift + Double click on battery symbol => reset battery to 100%



Appendix B: iTrain user forum

The iTrain user forum is there to inform you about and give you support on iTrain. It is available at http://berros.eu/itrain/forum/ via a web browser. It is not an open forum and only registered users can read it. You have to register with a self chosen username and password. Your registration will be verified by the webmaster so you have to choose a decent username or it might be refused. Initially it will start in English, but you can set the language and timezone you prefer.

The iTrain forum has been divided into different sections each containing a sub-forum for a specific language. Each sub-forum contains the same division so you can read and ask questions in your preferred language by choosing the right sub forum.

The first section 'Announcements' is a section to keep you up to date with the latest information about iTrain, such as releases and trade fairs. You cannot start an announcement, but only react on it. The same holds for the second section 'Frequently Asked Questions'.

The third section 'Support' is really for support questions. Here you can ask your own questions or respond to others. First choose the right category. Then use 'NewTopic' to add a new topic.

Always choose a good subject so your question can be found easily by other users. Also provide the information that is necessary for someone else to help you. In many cases this involves adding your own layout so people can see what you have been doing. The layout must first be saved within iTrain as a zip-file by ending the filename with .tcd.zip and then you can add it to the forum via the second tab 'Upload attachment'.

Try to formulate your question well and read it again before you submit it. Well formulated questions are answered more quickly, because there is less need for additional questions that will take more time. For additional questions not related to the current subject you should create a new topic and not continue the current thread. The questions also function as a database for new users in which they can find answers and the better the subject names are and the shorter and more to the point the topic is, the easier it is to find.

The last section 'Enhancement request' is for more experienced users who know what is possible in iTrain, but still lack some functionality or have some suggestions how to improve it. There is no guarantee that your suggestion will be included in iTrain within a certain time-frame, but all will be read and if possible discussed to get clear how it should be changed. The best ones will be considered to be implemented in the next or a later release.

In some cases you would like to exchange some details with another user that should not be visible to others. In that case send a PM (=Private message) to another user. Never put your address, phone or e-mail address in a topic if you want contact with other users. Just ask for contact and interested people can respond with a PM to exchange contact details.

Please be polite, patient and forgiving to other members both in asking and answering. We want to welcome new members, but also appreciate members who are spending a lot of time answering your questions and building this iTrain community. In case something happens that is not correct or really annoys you, please send an e-mail to

forum@berros.eu so we can intervene or solve it.